

## Solutions to the Extra Practice Problems for Chapter 6

1. The angle is  $51^\circ$  and the mass is  $0.92 \text{ kg}$ . For  $T_1$ , we use the fact that when two parallel lines are cut by a transversal, alternating interior angles are congruent. However, that still doesn't give us the physics angle for  $T_1$ . The physics angle adds to that angle to make exactly  $180^\circ$ , so it is  $139^\circ$ . For  $T_2$ , the alternating angle is also the physics angle, so its angle is  $\theta$ .

$$T_1 \cdot \cos(139^\circ) + T_2 \cdot \cos(\theta) + w \cdot \cos(270^\circ) = 0$$

$$(5.7 \text{ N}) \cdot \cos(139^\circ) + (6.8 \text{ N}) \cdot \cos(\theta) = 0$$

$$\cos(\theta) = \frac{-(5.7 \text{ N}) \cdot \cos(139^\circ)}{6.8 \text{ N}} = 0.63$$

$$\theta = \cos^{-1}(0.63) = 51^\circ$$

In the y-dimension:

$$T_1 \cdot \sin(139^\circ) + T_2 \cdot \sin(\theta) + w \cdot \sin(270^\circ) = 0$$

$$(5.7 \text{ N}) \cdot \sin(139^\circ) + (6.8 \text{ N}) \cdot \sin(51^\circ) - w = 0$$

$$w = (5.7 \text{ N}) \cdot \sin(139^\circ) + (6.8 \text{ N}) \cdot \sin(51^\circ) = 3.7 \text{ N} + 5.3 \text{ N} = 9.0 \text{ N}$$

But that's the weight, which is  $m \cdot g$ . Thus, we divide by  $g$  to get the mass, which is  $0.92 \text{ kg}$ .

2. The coefficient of kinetic friction is  $0.253$ . When it is given a shove, kinetic friction takes over, and if the velocity is constant, no matter what its value, Equation (6.6) applies and gives us the coefficient of kinetic friction.

$$\mu = \tan(\theta) = \tan(14.2^\circ) = 0.253$$

3. The coefficient of static friction is  $0.475$ . This is just like the experiment. Equation (6.6) will give us the coefficient of kinetic friction.

$$\mu = \tan(\theta) = \tan(25.4^\circ) = 0.475$$

4. The coefficient of kinetic friction is  $0.413$ . Since the box is accelerating, Equation (6.6) doesn't apply. Thus, we must sum up the forces, defining down the ramp as negative:

$$-m \cdot g \cdot \sin(\theta) + \mu_k \cdot m \cdot g \cdot \cos(\theta) = m \cdot a$$

$$-g \cdot \sin(\theta) + \mu_k \cdot g \cdot \cos(\theta) = a$$

We can now plug in the values we know, but remember that down the incline is defined as negative. Thus, the acceleration is negative, not positive.

$$-\left(9.81 \frac{\text{m}}{\text{s}^2}\right) \cdot \sin(25.4^\circ) + \mu_k \cdot \left(9.81 \frac{\text{m}}{\text{s}^2}\right) \cdot \cos(25.4^\circ) = -0.55 \frac{\text{m}}{\text{s}^2}$$

$$\mu_k \cdot \left(9.81 \frac{\text{m}}{\text{s}^2}\right) \cdot \cos(25.4^\circ) = -0.55 \frac{\text{m}}{\text{s}^2} + 4.21 \frac{\text{m}}{\text{s}^2}$$

$$\mu_k = \frac{3.66 \frac{\text{m}}{\text{s}^2}}{\left(9.81 \frac{\text{m}}{\text{s}^2}\right) \cdot \cos(25.4^\circ)} = 0.413$$

5. The acceleration is  $3.2 \text{ m/s}^2$  down the ramp. Whether it is moving up or down the box, it is moving, so only kinetic friction plays a role. Thus, we use the smaller coefficient of friction. Defining down the ramp as negative:

$$\begin{aligned} -\cancel{m} \cdot g \cdot \sin(\theta) + \mu_k \cdot \cancel{m} \cdot g \cdot \cos(\theta) &= \cancel{m} \cdot \mathbf{a} \\ -g \cdot \sin(\theta) + \mu_k \cdot g \cdot \cos(\theta) &= \mathbf{a} \end{aligned}$$

We can now plug in the values we know:

$$\begin{aligned} -\left(9.81 \frac{\text{m}}{\text{s}^2}\right) \cdot \sin(33.0^\circ) + (0.25) \cdot \left(9.81 \frac{\text{m}}{\text{s}^2}\right) \cdot \cos(33.0^\circ) &= \mathbf{a} \\ \mathbf{a} &= -5.34 \frac{\text{m}}{\text{s}^2} + 2.1 \frac{\text{m}}{\text{s}^2} = -3.2 \frac{\text{m}}{\text{s}^2} \end{aligned}$$

6. The acceleration is  $3.3 \text{ m/s}^2$ , and the tension in the string is  $0.85 \text{ N}$ . We can look at each box individually. For the first box, the force is to the right, which I will call positive. That means T is negative. Also, note that since force is in N, mass must be in kg:

$$1.2 \text{ N} + -T = (0.112 \text{ kg}) \cdot (\mathbf{a})$$

We have two unknowns, so looking at the second box, the only force acting on it is the tension in the string, which pulls to the right. That makes it positive.

$$T = (0.257 \text{ kg}) \cdot (\mathbf{a})$$

We can plug that in for T in the first equation:

$$\begin{aligned} 1.2 \text{ N} - (0.257 \text{ kg}) \cdot (\mathbf{a}) &= (0.112 \text{ kg}) \cdot (\mathbf{a}) \\ (0.369 \text{ kg}) \cdot \mathbf{a} &= 1.2 \text{ N} \\ \mathbf{a} &= \frac{1.2 \text{ N}}{0.369 \text{ kg}} = \frac{1.2 \frac{\text{kg} \cdot \text{m}}{\text{s}^2}}{0.369 \text{ kg}} = 3.3 \frac{\text{m}}{\text{s}^2} \end{aligned}$$

Now we can get tension:

$$T = (0.257 \text{ kg}) \cdot (\mathbf{a}) = (0.257 \text{ kg}) \cdot \left(3.3 \frac{\text{m}}{\text{s}^2}\right) = 0.85 \text{ N}$$

7. The maximum force is  $2.9 \text{ N}$ . Since  $T = 2.0 \text{ N}$  is the maximum value the string can hold, the first box's equation becomes:

$$F + -2.0 \text{ N} = (0.112 \text{ kg}) \cdot (\mathbf{a})$$

We have two unknowns, so looking at the second box, the only force acting on it is the tension in the chain, which pulls to the right. That makes it positive.

$$\begin{aligned} 2.0 \text{ N} &= (0.257 \text{ kg}) \cdot (\mathbf{a}) \\ \mathbf{a} &= \frac{2.0 \text{ N}}{0.257 \text{ kg}} = \frac{2.0 \frac{\text{kg} \cdot \text{m}}{\text{s}^2}}{0.257 \text{ kg}} = 7.8 \frac{\text{m}}{\text{s}^2} \end{aligned}$$

Putting that into the first equation:

$$F + -2.0 \text{ N} = (0.112 \text{ kg}) \cdot (7.8 \frac{\text{m}}{\text{s}^2})$$

$$F = 0.87 \text{ N} + 2.0 \text{ N} = 2.9 \text{ N}$$

8. No, it is not in rotational equilibrium. For that to happen, the sum of the torques must be zero. That's not possible here, since the second force is *parallel* to the lever arm. Thus, there is no perpendicular component to that force, so the torque it exerts is zero. Thus, there is only one force making a torque, which means the sum cannot be zero.

9. The mass is 1.4 kg. The 1.9-kg plane produces clockwise motion, so its torque is negative.

$$\tau_{\text{unknown}} + -\tau_{1.9\text{kg}} = 0$$

$$(m) \cdot \cancel{g} \cdot (9.8 \text{ cm}) - (1.9 \text{ kg}) \cdot \cancel{g} \cdot (7.2 \text{ cm}) = 0$$

$$m = \frac{(1.9 \text{ kg}) \cdot (7.2 \cancel{\text{cm}})}{9.8 \cancel{\text{cm}}} = 1.4 \text{ kg}$$

10. The plane must be 1.71 cm right of the axis of rotation. The planes on the right have a negative torque, while the one on the left is positive

$$\tau_{556\text{g}} + -\tau_{702\text{g}} + -\tau_{519\text{g}} = 0$$

$$(556 \text{ grams}) \cdot \cancel{g} \cdot (11.5 \text{ cm}) - (702 \text{ grams}) \cdot \cancel{g} \cdot (r_{702\text{g}}) - (519\text{grams}) \cdot \cancel{g} \cdot (10.0 \text{ cm}) = 0$$

$$r_{702\text{g}} = \frac{(556 \text{ grams}) \cdot (11.5 \text{ cm}) - (519 \text{ grams}) \cdot (10.0 \text{ cm})}{702 \text{ grams}}$$

$$r_{7.5\text{g}} = \frac{6,390 \text{ gram} \cdot \text{cm} - 5,190 \text{ gram} \cdot \text{cm}}{702 \text{ grams}} = \frac{1.20 \times 10^3 \cancel{\text{gram}} \cdot \text{cm}}{702 \cancel{\text{grams}}} = 1.71 \text{ cm}$$